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Publisher's version / Version de l'éditeur:

The 18th IEEE International Conference on Tools with Artificial Intelligence (ICTAI06) [Proceedings], 2006

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Liang, H., Zhang, H., Yan, Y.
November 2006

* published at The 18th IEEE International Conference on Tools with
Artificial Intelligence (ICTAI06). November 13-15, 2006. Washington D.C.,
USA. NRC 48783.

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Decision Trees for Probability Estimation: An Empirical Study

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Abstract

Accurate probability estimation generated by learning models is desirable in some practical applications, such as medical diagnosis. In this paper, we empirically study traditional decision-tree learning models and their variants in terms of probability estimation, measured by Conditional Log Likelihood (CLL). Furthermore, we also compare decision tree learning with other kinds of representative learning: naïve Bayes, Naïve Bayes Tree, Bayesian Network, K-Nearest Neighbors and Support Vector Machine with respect to probability estimation. From our experiments, we have several interesting observations. First, among various decision-tree learning models, C4.4 is the best in yielding precise probability estimation measured by CLL, although its performance is not good in terms of other evaluation criteria, such as accuracy and ranking. We provide an explanation for this and reveal the nature of CLL. Second, compared with other popular models, C4.4 achieves the best CLL. Finally, CLL does not dominate another well-established relevant measurement AUC (the Area Under the Curve of Receiver Operating Characteristics), which suggests that different decision-tree learning models should be used for different objectives. Our experiments are conducted on the basis of 36 UCI sample sets that cover a wide range of domains and data characteristics. We run all the models within a machine learning platform - Weka.

1. Introduction

In the areas of machine learning and data mining, classification accuracy has been established as the major criterion to evaluate learning models. However, it completely ignores probability estimation generated by models as long as misclassification does not occur. In many real applications, accurate probability estimation is crucial compared with merely classifying unlabeled samples into a fixed number of categories. For instance, in cost-sensitive learning,

the optimal prediction for an unlabeled sample s_t is the class c_j that minimizes [3]

$$h(s_t) = \arg \min_{c_j \in C} \sum_{c_i \in C - c_j} \hat{p}(c_i | s_t) C(c_j, c_i), \quad (1)$$

where $C(c_j, c_i)$ indicates the cost of misclassifying s_t into c_i in a cost matrix C . One can observe that the metric function directly relies on accurate probabilities.

In practice, however, the true probability of unlabeled samples is often unknown given a sample set with class labels. Is there any way to measure the probability estimation yielded by a model when the true probability is unknown? Fortunately, the answer is yes. Recently, *Conditional Log Likelihood* (CLL) has been proposed and used for this purpose [4, 5, 6]. In Equation 2, a formal CLL definition is given.

$$CLL(\Gamma | \mathbf{S}) = \sum_{t=1}^n \log P_{\Gamma}(C | s_t), \quad (2)$$

where Γ is a learning model and \mathbf{S} is a sample set with n samples. [4] described that maximizing Equation 2 amounts to best approximate the conditional probability of C given each unlabeled sample s_t , and is equivalent to minimizing the *conditional cross-entropy*.

Another recently widely-used alternative is *the Area Under the ROC Curve*, or simply AUC [16]. Assume that a learning model Γ produces the probability $\hat{p}(c | s_t)$ for each unlabeled sample s_t , and that all the unlabeled samples are ranked based on $\hat{p}(c | s_t)$. For binary classification, AUC can be easily computed as follows [7].

$$AUC(\Gamma | \mathbf{S}) = \frac{S_+ - n_+(n_+ + 1)/2}{n_+ n_-}, \quad (3)$$

where n_+ and n_- are the numbers of positive and negative samples respectively, and $S_+ = \sum r_i$, where r_i is the rank of i_{th} positive sample in the ranking. It can be observed that AUC essentially measures the quality of a rank. More precisely, the more negative samples that are listed

preceding positive samples, the larger AUC value we will get. Note that ranking is based on probability estimation, and it would be accurate if the probabilities are accurate. Thus, AUC can be also used to evaluate the probability estimation of a learning model. However, it seems that AUC is only an indirect evaluation metric.

The liaison between the above two metrics is demonstrated by two instances. Assume that s_+ and s_- are a positive and a negative sample respectively, and their true class probabilities are $p(+|s_+) = 0.6$ and $p(-|s_-) = 0.5$. A learning model Γ , which yields class probability estimates $\hat{p}(+|s_+) = 0.5$ and $\hat{p}(+|s_-) = 0.2$, gives a correct order of s_+ and s_- in the ranking that results in a good AUC value. Notice that the probability estimation for s_- is far inaccurate. However, obtaining a relatively better probability estimate could not guarantee a good AUC result. Suppose that another model Θ outputs probability estimates for s_+ and s_- as $\hat{p}(+|s_+) = 0.6$ and $\hat{p}(+|s_-) = 0.6$. As we can see Θ works better than Γ in terms of CLL, but it will generate a worse AUC result since s_+ and s_- share the same positive probability and will be ordered randomly, which could greatly aggravate the AUC value.

Decision trees are well known as a typical learning model for classification accuracy, although it has been observed that traditional decision trees produce poor probability estimation [18]. A variety of methods have been proposed to learn decision trees for accurate probability estimation [17, 14, 12], and AUC is often used as the measurement. Huang and Ling [9] empirically studied the performance of various learning models in terms of AUC. As we notice, it seems that CLL is a more straightforward measurement to evaluate learning models with respect to probability estimation. How about the performance of learning models in terms of CLL? What is the relation between CLL and AUC? These are the key motivations of the paper. We primarily focus on decision tree learning. We first systematically investigate the use of CLL as the performance metric to evaluate tree-related models. In particular, as a case study, we compare C4.4 (the improvement version of C4.5 for better probability estimation) and its variants, with C4.5 (traditional decision tree) and its variants in terms of CLL performance. Second, we also experimentally study several commonly-used models, such as TAN and SVM, with the purpose of which model is currently best in generating accurate probability estimation. The paper concludes with several observations. (1) Among tree-related models, C4.4 is best in yielding accurate probability estimation. (2) In the domain of classic learning models, C4.4 is also the best in terms of accurate probability estimation. (3) The inductive associations between AUC and CLL under decision tree learning paradigms are as well introduced.

This paper is outlined as follows: Section 2 reviews recent work on improving decision trees for better probability

estimation. Section 3 introduces the experiment configuration and methodology. In Section 4 empirical results are analyzed and discussed, and we will close our paper in Section 5 by drawing our inclusions and presenting the further work.

2. Optimizing Probability Estimation

In a decision boundary-based theory, an explicit decision boundary is induced from a set of labeled samples, and an unlabeled sample s_t is categorized into class c_j if s_t falls into the decision area corresponding to c_j . However, traditional decision trees, such as C4.5 [20] and ID3 [19], have been observed to produce poor probability estimation [18]. Normally, decision trees produce probabilities by computing the class frequencies from the sample sets at leaves. For example, assuming there are 30 samples at a leaf, 20 of which are in the positive class and others belong to the negative class. Therefore, each unlabeled sample that falls into that leaf will be assigned the same probability estimates ($\hat{p}_+(+|s_t) = 0.67$ (20/30) and $\hat{p}_-(-|s_t) = 0.33$ (10/30)). Equation 4 gives a formal expression.

$$\hat{p}(c_j|s_t) = \frac{n_{c_j}}{n}, \quad (4)$$

here, n_{c_j} is the number of samples that belong to class c_j and n is the total number of samples at this leaf. Due to using *Information Gain* or *Gain Ratio* as splitting metrics, traditional tree inductive algorithms prefer a small tree with a substantial amount of samples at leaves and try to make leaves pure. This will incur two major problems. (1) Many unlabeled samples will share the same probability estimates, which definitely biases against producing accurate probability estimation. In addition, the resulting probabilities will be systematically shifted towards zero or one. (2) Decision trees adopt some pruning techniques, such as *expected error pruning* or *pessimistic error pruning*, for high classification accuracy. However, some branches, which make no sense of improving accuracy but contribute to get accurate probability estimation, will be removed.

Because of this, learning decision trees that accurately estimate the probability of class membership, called *Probability Estimation Trees* (PETs), has attracted much attention. Provost and Domingos [17] presented a few of such techniques to modify C4.5 for better probability estimation. First, using *Laplace* correction at leaves, probability estimates can be smoothed towards the prior probability distribution. Second, by turning off pruning and collapsing in C4.5, decision trees can generate larger trees to give more precise probability estimation. The final version is called C4.4. They also pointed out that *bagging*, an ensemble method that most of the improvement is due to aggregation of probabilities of a suite of trees, could greatly calibrate probability estimation of decision trees.

Ferri et al. [14] introduced another approach, call m -Branch, to tune probability estimates at leaves. m -Branch is a recursive root-to-leaf extension of the m probability estimation, in which, for each leaf, the probability estimates are generated by propagating the probability estimates of each of its parent nodes from the root down to itself. Equation 5 is the formal expression of m -Branch method:

$$\hat{p}_{child}(c_j|s_t) = \frac{n_{c_j} + m * \hat{p}_{parent}(c_j|s_t)}{\sum_{c_j \in C} n_{c_j} + m}, \quad (5)$$

where parameter m is adjusted by the depth and cardinality of the node, and n_{c_j} is the number of samples that belong to class c_j within the node.

Ling and Yan [12] presented their work to augment decision trees with respect to better AUC. They described a novel algorithm, in which, for any given unlabeled sample s_t , instead of using the labeled samples at the leaf where s_t falls into, the probability estimates are the averages of probability estimates from all the leaves of this tree. The contribution of each leaf is decided by the number of unequal parent attribute values (parent attributes are defined as the attributes on the path from the root to a leaf) that the leaf has, compared to s_t .

Deploying a kernel model at each leaf to produce distinct probability estimates is also an alternative solution to overcome the deficiencies of decision trees. Kohavi [10] proposed a hybrid model, called *Naïve Bayes Tree* (NBTree), which uses decision tree as the general structure and deploys naïve Bayes at the leaves. The intuition behind it is that: in comparison with decision trees, naïve Bayes works relatively better when the sample set is small. [10] proved that NBTree greatly improves the classification accuracy, but it didn't mention the probability estimation performance of NBTree. Based on the labeled samples at a leaf, NBTree denotes $\hat{p}(c_j|s_t)$ as below:

$$\hat{p}(c_j|\mathbf{A}(L)) = \alpha \hat{p}(\mathbf{A}_1(L)|c_j, \mathbf{A}_P(L)) \hat{p}(c_j|\mathbf{A}_P(L)), \quad (6)$$

where α is a normalization factor. $\mathbf{A}(L)$ is the combined set of leaf attributes $\mathbf{A}_1(L)$ and path attributes $\mathbf{A}_P(L)$. All decomposed terms are conditional probabilities of $\mathbf{A}_P(L)$. $\hat{p}(c_j|\mathbf{A}_P(L))$ is the conditional probability on path attributes. $\hat{p}(\mathbf{A}_1(L)|c_j, \mathbf{A}_P(L))$ is the naïve Bayes deployed at this leaf. From the conditional independence assumption of naïve Bayes, the following equation stands: $\hat{p}(\mathbf{A}_1(L)|c_j, \mathbf{A}_P(L)) = \prod_{i=1}^n \hat{p}(A_{li}(L)|c_j, \mathbf{A}_P(L))$ where $A_{li}(L)$ is an individual leaf attribute and n represents the number of leaf attributes.

Another related work involves *Bayesian networks* [15]. Bayesian networks are directed acyclic graphs that encode conditional independence among a set of random variables. Each variable is independent of its non-descendants in the graph given the state of its parents. *Tree Augmented Naïve*

Bayes (TAN), proposed by [4], approximates the interaction between attributes by using a tree structure imposed on the naïve Bayesian framework. Indeed, decision trees divide a sample space into multiple subspaces and local conditional probabilities are independent among those subspaces. Therefore, attributes in decision trees can repeatedly appear, while TAN describes the joint probabilities among attributes, so each attribute appears only once.

3. Experiments

3.1. Model Introduction and Organization

Most methods for improving decision trees aim at obtaining their probability estimation measured by AUC. However, can they also produce better results in CLL? And how about other classical models work with reference to CLL? We conducted an empirical study to answer a series of relevant questions.

The details of models compared in our experiments are depicted as follows.

C4.5-L: C4.5 (traditional decision tree [20]) with *Laplace* correction at leaves. Here, we use *Laplace* correction at leaves to avoid the zero-frequency problem.

C4.5-L&B: C4.5 with *bagging* and *Laplace* correction at leaves.

C4.4: an improved decision tree model for better probability estimation [17].

C4.4-B: C4.4 with *bagging*.

C4.5-M: C4.5 with m -Branch [14] applied.

C4.4-M: C4.4 with m -Branch applied.

C4.5-LY: C4.5 with the *Ling&Yan's* algorithm [12] applied.

C4.4-LY: C4.5 with the *Ling&Yan's* algorithm applied.

NB: naïve Bayes.

TAN: an extended tree-like naïve Bayes [4]. The improved *ChowLiu* algorithm is used to learn the structure.

NBTree: the hybrid model of decision tree and naïve Bayes [10].

KNN-5: a typical lazy model that finds k nearest labeled samples as the neighbors of an unlabeled sample s_t . KNN generates probability estimation via simply voting among the class labels in the neighborhood, described in Equation 7.

$$\hat{p}(c_j|s_t) = \frac{1 + \sum_{i=1}^n I\{c_i = c_j\} \hat{w}_i}{o + \sum_{i=1}^n \hat{w}_i}, \quad (7)$$

where c_i is the class label of a neighbor with index i , the indicator function $I\{x = y\}$ is one if $x = y$ and zero otherwise, \hat{w}_i is the weight for the neighbor (the default value is one) and o represents the number of class values. We assign $k = 5$ in our experiments.

SVM: with the help of linear kernels, the *sequential minimal optimization* algorithm has been used to train a SVM model. We use logistic regression models to improve the yielded probabilities. [8] and [21] have introduced in particular the procedure of generating multi-class probability estimation for SVM.

We conducted two groups of experiments. First, we systematically studied the performances of tree-related models in producing accurate probability estimation. In this group, C4.5, C4.4 and their PET variants (C4.5-L, C4.5-M, C4.5-LY, C4.5-L&B, C4.4-M, C4.4-LY and C4.4-B) were compared. Then, we empirically learned the efficacy of several popular learning models for probability estimation. C4.4, NBTree, NB, TAN, KNN-5 and SVM had been considered in the second group. Furthermore, we also analyzed the behaviors of these classical models provided that the sample set is a large or binary-class one.

3.2. Experiment Setup and Methodology

For the purpose of our study, we used 36 well-recognized sample sets recommended by *Weka* [22]. Table 1 is a brief description of these sample sets. All sample sets came from the UCI repository [1]. The preprocessing stages of sample sets were carried out within the *Weka* platform, mainly including four steps:

1. Applying the filter of *ReplaceMissingValues* in *Weka* to replace the missing values of attributes.
2. Applying the filter of *Discretize* in *Weka* to discretize numeric attributes. Therefore, all the attributes are treated as nominal.
3. It is well known that, if the number of values of an attribute is almost equal to the number of samples in a sample set, this attribute does not contribute any information to classification. So we used the filter of *Remove* in *Weka* to delete these attributes. Three occurred within the 36 sample sets, namely *Hospital Number* in sample set *Horse-colic.ORIG*, *Instance Name* in sample set *Splice* and *Animal* in sample set *Zoo*.
4. Due to the relatively high time complexity of KNN and SVM, we apply the filter of unsupervised *Resample* in *Weka* to re-select sample set *Letter* and generate a new sample set named *Letter-2000*. The selection rate is 10%.

Besides, in our experiments, *Laplace* correction was applied as one of the following forms. Assuming that there are n_{c_j} samples that have the class label as c_j , t total samples and k class values in a sample set. The frequency-based probability estimation calculates the estimated probability by $\hat{p}(c_j) = \frac{n_{c_j}}{t}$. The Laplace estimation calculates it as

Table 1. Description of sample sets used for the experiments. We downloaded these sample sets in the format of *arff* from the main web page of *Weka*.

Data Set	Size	Attr.	Classes	Missing	Numeric
anneal	898	39	6	Y	Y
anneal.ORIG	898	39	6	Y	Y
audiology	226	70	24	Y	N
autos	205	26	7	Y	Y
balance	625	5	3	N	Y
breast ◊	286	10	2	Y	N
breast-w ◊	699	10	2	Y	N
colic ◊	368	23	2	Y	Y
colic.ORIG ◊	368	28	2	Y	Y
credit-a ◊	690	16	2	Y	Y
credit-g * ◊	1000	21	2	N	Y
diabetes ◊	768	9	2	N	Y
glass	214	10	7	N	Y
heart-c	303	14	5	Y	Y
heart-h	294	14	5	Y	Y
heart-s ◊	270	14	2	N	Y
hepatitis ◊	155	20	2	Y	Y
hypoth. *	3772	30	4	Y	Y
ionosphere ◊	351	35	2	N	Y
iris	150	5	3	N	Y
kr-vs-kp * ◊	3196	37	2	N	N
labor ◊	57	17	2	Y	Y
letter-2000 *	2000	17	26	N	Y
lymph	148	19	4	N	Y
mushroom * ◊	8124	23	2	Y	N
p.-tumor	339	18	21	Y	N
segment *	2310	20	7	N	Y
sick * ◊	3772	30	2	Y	Y
sonar ◊	208	61	2	N	Y
soybean	683	36	19	Y	N
splice *	3190	62	3	N	N
vehicle	846	19	4	N	Y
vote ◊	435	17	2	Y	N
vowel *	990	14	11	N	Y
waveform-5000 *	5000	41	3	N	Y
zoo	101	18	7	N	Y

* indicates a large sample set; ◊ indicates a binary-class sample set

$\hat{p}(c_j) = \frac{n_{c_j} + 1}{t + k}$. In the Laplace estimation, $\hat{p}(a_i | c_j)$ is calculated by $\hat{p}(a_i | c_j) = \frac{n_{ic_j} + 1}{n_{c_j} + v_i}$, where v_i is the number of values of attribute A_i and n_{ic_j} is the number of samples in class c_j with $A_i = a_i$.

We implemented AUC metric, CLL metric, m -Branch method, *Ling&Yan*'s algorithm within *Weka*, and used the current versions of learning models and *bagging* method in *Weka*. We learned that using the percentage of the subset as the confusion factor in *Ling&Yan*'s algorithm was better than the proposed optimal parameter 0.3. Therefore, we used a new confusion factor in our experiments. Multi-class AUC has been calculated by M -measure [7]. In all experiments, the AUC and CLL results for each model were measured via a 10-fold cross validation 10 times. Runs with various models were carried out on the same train sets and evaluated on the same test sets. In particular, the cross-validation folds were the same for all the experiments on each sample set. Finally, we conducted two-tailed t -test [13] with a significantly different probability of 0.95,

which means that we speak of two results as being “significantly different” only if the difference is statistically significant at the 0.05 level according to the corrected two-tailed t -test. Also, each entry $w/t/l$ in all t -test tables indicates that the model in the corresponding row wins w sample sets, ties in t sample sets, and loses l sample sets, in contrast with the model in the corresponding column.

4. Result Analysis and Discussion

In Table 2 and its t -test summary Table 3, **C4.4 is the optimal option among decision tree families when accurate probability estimation is desired.** Compared with traditional decision trees, C4.4 wins C4.5-L in 10 sample sets, ties in 21 sample sets and loses 5 sample sets. Note that C4.4 adopts both *Laplace* correction at leaves and turning off pruning, therefore, we learned that stopping pruning could significantly improve the quality of probability estimation. Compared with bagged decision trees, C4.4 wins C4.5-L&B in 16 sample sets and loses 9 samples sets; C4.4 wins C4.4-B in 20 sample sets and loses 8 sample sets. *Bagging* is a voting strategy among a group of candidate trees. [17] has proved that *bagging* is useful in improving probability-based ranking. However, according to our observation of the empirical results of C4.4 and C4.4-B, *bagging* is not profitable in producing precise probability estimation. In addition, the comparison results of C4.5-L and C4.5-L&B are also persuadable: C4.5-L wins C4.5-L&B in 16 sample sets and loses 8 sample sets. Compared to decision trees with m -Branch, C4.4 outperforms C4.5-M and C4.4-M in 15 sample sets and 13 sample sets respectively, and loses 6 sample sets for both of them. For applying *Ling&Yan*’s algorithm on decision trees, C4.4 is significantly better than C4.5-LY and C4.4-LY in 33 sample sets and loses no sample set. Thus, we can learn that neither m -Branch method nor *Ling&Yan*’s algorithm could calibrate decision trees for accurate probabilities.

Most methods mentioned in Section 2 are intended to improve probability-based ranking measured by AUC. AUC is a relative evaluation standard. In other words, the correctness of ranking, which depends on the relative position of a sample among a set of others, determines the final result. CLL is directly calculated via adding up log values of probability estimates generated by a learning model for unlabeled samples (see Equation 2). Therefore, **in the diagram of decision tree learning, CLL and AUC represent two aspects of probability estimation: reliability and resolution.** Dawid [2] described these two conceptual criteria for studying how *effective* probability predictions are. *Reliability* describes the probability estimation should be reliable and accurate, that is, when we assign a positive class probability $\hat{p}(+|e)$ to an event e , there should be roughly $1 - \hat{p}(+|e)$ of the negative class probability for the event

not occurring. *Resolution* presents that events should be easily ranked in terms of their probabilities. As a result, for decision tree learning, CLL can be employed as evaluating the reliability of probability estimation, and AUC will be applied for scaling its resolution performance. In our experiments, we also obtained the AUC values of all decision tree models. Table 6 shows the t -test results. We have two valuable observations as follows.

1. Although C4.4 performs best in terms of CLL, all the variants of C4.4 and C4.5 proposed for improving AUC outperforms C4.4 in terms of AUC (see Table 6), which repeated the research results reported by other researchers.
2. Among all the models, C4.4-B achieves the best performance on AUC. This means bagging is an effective technique in terms of improving AUC. However, as we noticed before, bagging is not effective in improving CLL.

Now we re-exam CLL in Equation 2. So far, we use the real-world sample sets for our empirical study, i.e. we do not know the real sample distributions. Equation 2 shows that if one model gives higher estimation of $\hat{p}(c_j|s_t)$ than another, its CLL will be higher. Therefore, CLL favors a model that gives higher probability estimation no matter what the true probability is, since the true probability does not even appear in CLL. Indeed, when using CLL, we imply the assumption that sample s_t in class c_j has probability $p(c_j|s_t) = 1$ and $p(-c_j|s_t) = 0$, thus, there is no surprise that CLL favors a model giving higher probability estimation. This can explain why C4.4 has better CLL performance than C4.4-B because C4.4 tends to have pure nodes, which means high probability estimation. but bagging or other smoothing techniques that tend to smooth the probabilities to avoid high variance. Therefore, CLL is just an indirect evaluation to true probabilities. We can also conclude that neither CLL nor AUC dominates each other.

In Table 4 and Table 5, we compare C4.4 with non-tree models in terms of CLL. C4.4 achieves significant improvement over NB in 17 sample sets and loses 5 sample sets. As an extension of NB in presenting more joint probability distribution, TAN still works poorly compared with C4.4 in 10 sample sets and loses 7 sample sets. Furthermore, t -test results in Table 5 indicates that extending the structure of NB to explicitly represent attribute dependencies (in order to relax the conditional independence assumption of NB) is a good way to improve the performance of probability estimation for NB. TAN achieves substantial progress over NB in 16 sample sets and loses only 3 sample sets. For lazy learning models, C4.4 is better than KNN with $k=5$ in 12 sample sets. We also conducted a group of comparisons between C4.4 and KNN with $k=10, 30$ and 50 . Experiment results suggested that the bigger k is, the worse

KNN performs in terms of CLL. Due to lack of space, we didn't show the results of other KNN models with different values of k . NBTree is proven to be efficient in classification accuracy, but from the results of t -test, it doesn't work very well compared with other typical models, and is just competitively with NB. Some work [11] has been done to ameliorate NBTree for precise probability estimation, where CLL is used as the splitting metric to direct the tree growth process. Although SVM doesn't work better than C4.4 (wins 7 sample sets and loses 12 sample sets), it is still better than other models, such as NBTree and KNN-5, and competitive with TAN (wins 7 sample sets and loses 8 sample sets). Besides, in AUC comparisons (Table 7), SVM and TAN achieve better results than others.

Empirical results on large sample sets in form of CLL absolute values have been demonstrated in Figure 1. We are especially interested in seeing the actual CLL values on large sample sets, because these data sets demonstrate practical cases we can meet. We choose ten sample sets from UCI repository on the condition that the number of samples in each set is above 900. In Figure 1, From *No1* to *No10* respectively denote the sample sets as *German-credit*, *Hypothyroid*, *Kr-vs-kp*, *Letter-2000*, *Mushroom*, *Segment*, *Sick*, *Splice*, *Vowel*, *Waveform-5000*. The plot explored the

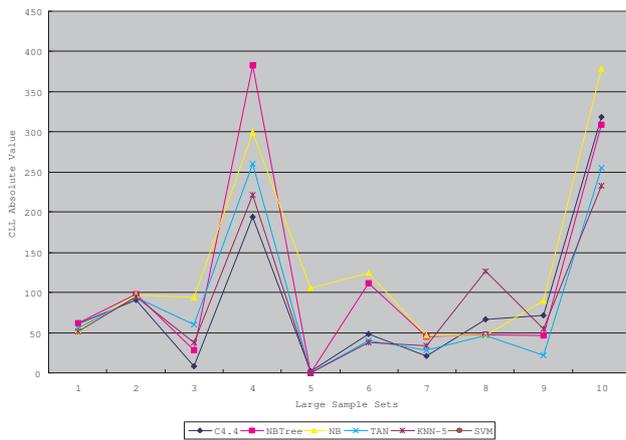


Figure 1. CLL performance curve on large sample sets

behaviors of classic models when a substantial amount of data is supplied. As we can observe that C4.4 works consistently better than others (the lowest learning curve), which stands that C4.4 is the optimal candidate for real-world domain problems. One valuable observation is that TAN and SVM also work well based on these sample sets. Therefore, TAN and SVM are good options for the cases where classification accuracy plays an important role as well in practice.

Experiments on binary-class sample sets have been also conducted by use of sixteen UCI sample sets: *Breast-cancer*, *Wisconsin-breast*, *Horse-colic*, *Colic.ORIG*, *Credit-rating*, *German-credit*, *Diabetes*, *Heart-statlog*, *Hepatitis*, *Ionosphere*, *Kr-vs-kp*, *Labor*, *Mushroom*, *Sick*, *Sonar*, *Vote* (listed from *No1* to *No16* in Figure 2). Binary-class sample sets are interesting for us because AUC can be easily calculated for these cases and we can verify results by observing the probability assignments. Figure 2 investigated the per-

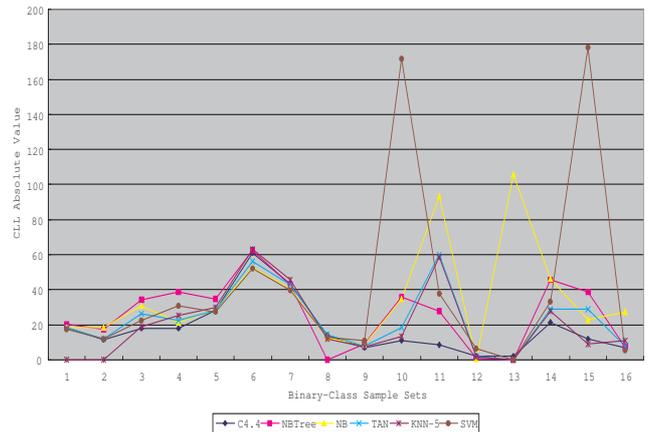


Figure 2. CLL performance curve on binary-class sample sets

formances of the same models measured by CLL absolute values, and showed that C4.4 is the best option for binary classification problems. In addition, as the plot shows, NB works poorly in some sample sets, such as *No11* and *No13*, where the conditional independence assumption is heavily violated. NBTree and TAN have both relaxed this assumption in two different ways (encoding conditional independence within tree structure or augmenting the representation ability of joint distribution), and the curves support that NBTree and TAN work better compared with NB.

5. Conclusions and Future Work

Precise probability estimation provided by learning models is crucial in many real-world applications. In this paper, we conduct a systematically experimental study on the probability estimation performances of a group of decision tree variants and other state-of-the-art models, such as SVM and TAN, by use of a newly proposed model quality measurement – CLL. Experiments convince us that C4.4 is the best model for CLL among all other models. We point out that CLL is an indirect evaluation of probability estimation and it could work for the real world cases when the true

probability distribution is unknown, however, it favors models which give high probability estimation. We analyze the relationship between AUC and CLL for learning tasks. We include that neither of them dominates the other. For further research, we are going to make similar analyses on artificial data sets with known probability distribution. This will enable us to theoretically analyze the properties of CLL in detail and make a comprehensive contrast between CLL and AUC.

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Table 2. Experiment results for C4.4 versus decision tree variants: CLL & standard deviation.

Sample Set	C4.4	C4.5-L	C4.5-M	C4.5-LY	C4.5-L&B	C4.4-M	C4.4-LY	C4.4-B
anneal	-7.84±2.58	-8.49±3.22	-8.99±4.98	-73.17±2.11●	-12.24±1.85●	-8.55±4.96	-74.37±2.16●	-13.74±1.78●
anneal.ORIG	-22.17±3.74	-25.19±3.95●	-25.24±5.74●	-86.49±2.66●	-34.24±4.07●	-22.97±5.44	-87.94±1.47●	-40.13±4.44●
audiology	-15.37±3.39	-17.23±3.63●	-24.38±9.27●	-63.11±1.70●	-32.89±3.24●	-23.23±8.82●	-63.14±1.59●	-35.95±3.02●
autos	-13.14±2.31	-14.36±2.58●	-15.84±2.87●	-33.58±1.11●	-23.60±2.27●	-15.46±2.61●	-33.76±1.09●	-24.35±2.13●
balance-scale	-52.78±4.03	-56.05±3.74●	-56.36±3.47●	-55.36±0.65	-45.34±2.74○	-53.26±3.37	-54.50±0.66	-46.71±2.46○
breast-cancer	-18.56±2.70	-16.27±1.84○	-16.20±1.74○	-17.33±0.60	-16.31±1.82○	-17.59±2.57○	-17.25±0.61	-17.07±2.13○
breast-w	-11.17±3.39	-12.10±4.64	-13.06±4.34	-43.80±2.38●	-9.78±3.12	-12.42±3.92	-44.06±1.81●	-10.13±2.50
colic	-17.80±4.31	-15.53±3.98○	-15.32±3.85○	-21.42±0.69●	-14.88±3.75○	-16.59±5.80	-21.39±0.69●	-15.18±3.36○
colic.ORIG	-17.66±3.19	-16.25±2.83	-16.06±2.38○	-22.60±0.45●	-15.26±2.39○	-16.71±2.75○	-22.60±0.45●	-16.09±2.26○
credit-a	-28.06±4.92	-25.88±5.08	-25.46±5.01○	-39.36±1.46●	-24.26±5.01○	-25.75±6.40○	-38.58±1.06●	-26.58±4.14
credit-g	-61.03±5.85	-56.37±4.20○	-55.20±3.66○	-62.07±0.62	-52.63±4.04○	-57.22±5.97○	-61.95±0.62	-53.68±3.87○
diabetes	-43.05±4.79	-41.09±5.25	-40.67±4.71	-49.91±0.51●	-39.20±4.83○	-40.71±4.77○	-49.36±0.45●	-40.19±4.08○
glass	-21.02±2.70	-21.71±2.64	-22.77±3.18	-34.26±0.96●	-27.26±1.99●	-22.45±3.27	-34.16±0.99●	-29.77±1.98●
heart-c	-15.85±3.68	-15.16±3.21	-15.28±3.15	-30.30±0.84●	-18.68±2.85●	-15.46±4.16	-30.54±0.77●	-25.93±2.79●
heart-h	-14.78±3.16	-14.66±3.27	-14.57±3.32	-30.23±1.08●	-16.03±3.20	-14.00±4.10	-30.15±1.03●	-24.12±3.09●
heart-statlog	-14.00±3.33	-13.09±3.49	-12.94±3.37	-16.63±0.39●	-12.37±2.50	-13.09±3.76	-16.63±0.37●	-12.61±2.15○
hepatitis	-6.81±2.51	-7.22±2.02	-7.08±1.81	-8.99±0.59●	-6.39±1.81	-6.87±2.78	-8.58±0.59●	-6.20±1.64
hypothyroid	-90.14±5.73	-107.41±6.68●	-108.42±6.69●	-264.34±9.67●	-98.88±7.46●	-92.18±13.03	-229.80±4.85●	-104.87±5.70●
ionosphere	-10.77±3.04	-11.42±3.04	-11.96±2.77	-21.71±0.39●	-9.58±2.42	-11.17±3.31	-21.61±0.37●	-9.42±2.08○
iris	-3.63±1.35	-3.59±1.38	-3.97±1.29●	-15.21±0.27●	-3.70±1.26	-4.12±1.29●	-15.40±0.25●	-4.01±1.23●
kr-vs-kp	-8.65±3.50	-10.00±3.93	-11.21±3.95●	-182.92±2.13●	-9.01±3.15	-9.82±3.55●	-182.42±1.80●	-7.92±2.75
labor	-2.22±1.28	-2.20±1.29	-2.43±1.17	-3.18±0.45●	-2.26±1.20	-2.32±1.34	-3.16±0.44●	-2.13±0.95
letter-2000	-193.65±10.88	-221.99±10.86●	-299.86±18.93●	-627.84±0.90●	-434.10±10.82●	-296.32±18.62●	-627.85±0.90●	-454.15±9.78●
lymph	-7.75±2.64	-7.69±2.80	-8.13±2.90	-13.78±0.91●	-8.79±2.12	-7.91±2.85	-13.91±0.88●	-9.85±1.85●
mushroom	-2.10±0.19	-2.10±0.19	-3.13±0.45●	-432.76±1.84●	-2.18±0.20	-3.13±0.45●	-432.76±1.84●	-2.18±0.20
primary-tumor	-50.98±3.70	-55.94±4.41●	-76.43±10.23●	-94.81±1.26●	-79.81±3.67●	-75.42±9.65●	-95.96±1.11●	-82.41±3.45●
segment	-48.76±7.07	-55.68±7.96●	-58.87±9.17●	-405.57±2.21●	-85.44±6.63●	-55.80±8.75●	-406.77±1.96●	-97.61±6.49●
sick	-21.10±5.56	-26.75±8.37●	-26.40±8.41●	-152.85±4.45●	-25.91±8.29	-19.38±6.43○	-152.99±3.69●	-19.66±4.67
sonar	-11.91±2.45	-12.54±2.48	-12.20±2.15	-13.87±0.38●	-10.92±1.72	-11.50±2.28	-13.88±0.39●	-10.76±1.50
soybean	-18.39±3.31	-19.28±3.53	-21.01±4.12●	-163.56±1.85●	-56.99±4.32●	-20.72±4.13●	-164.86±1.71●	-61.37±4.69●
splice	-66.48±8.24	-66.02±10.77	-70.25±11.45	-249.68±1.73●	-68.80±8.25	-70.78±10.83●	-250.19±1.64●	-78.71±6.91●
vehicle	-55.24±4.50	-57.28±4.96	-61.25±5.29●	-108.01±1.04●	-64.57±3.42●	-62.53±5.14●	-107.69±1.08●	-70.21±3.09●
vote	-6.90±3.56	-6.09±3.41○	-6.11±3.37	-18.28±1.29●	-6.09±3.22○	-6.67±4.10	-19.30±0.78●	-6.10±3.25
vowel	-71.55±6.18	-81.10±6.40●	-96.68±8.20●	-226.42±0.65●	-144.03±5.32●	-95.45±8.10●	-226.45±0.63●	-152.25±4.88●
waveform-5000	-318.55±12.98	-306.45±14.10○	-308.21±14.19○	-509.37±1.08●	-307.92±12.02○	-329.01±13.84●	-509.67±1.04●	-351.30±9.38●
zoo	-2.74±1.28	-2.90±1.30	-3.35±1.68	-13.35±0.68●	-4.55±1.02●	-3.18±1.65	-13.76±0.59●	-4.59±1.00●
average	-38.13±4.11	-39.81±4.37	-43.76±5.09	-116.84±1.44	-50.69±3.83	-43.33±5.41	-116.04±1.18	-54.66±3.38

●, ○ statistically significant degradation or improvement compared with C4.4

Table 3. Summary on *t*-test of CLL experiment results on decision tree variants.

Models	C4.5-L	C4.5-M	C4.5-LY	C4.5-L&B	C4.4-M	C4.4-LY	C4.4-B
C4.5-M	2/18/16						
C4.5-LY	0/2/34	0/1/35					
C4.5-L&B	8/12/16	9/14/13	36/0/0				
C4.4-M	4/21/11	7/27/2	34/2/0	13/14/9			
C4.4-LY	0/2/34	0/1/35	9/18/9	0/1/35	0/3/33		
C4.4-B	6/11/19	7/13/16	35/1/0	2/13/21	6/12/18	35/1/0	
C4.4	10/21/5	15/15/6	33/3/0	16/11/9	13/17/6	33/3/0	20/8/8

Table 4. Experiment results for C4.4 versus several classical models: CLL & standard deviation.

Sample Set	C4.4	NBTree	NB	TAN	KNN-5	SVM
anneal	-7.84±2.58	-18.46±17.63	-14.22±6.16 ●	-6.29±5.36	-8.22±2.80	-3.52±5.32 ○
anneal.ORIG	-22.17±3.74	-33.33±16.32●	-23.58±5.60	-19.55±6.90	-27.40±5.44 ●	-23.25±6.33
audiology	-15.37±3.39	-95.28±41.89●	-65.91±24.28●	-67.19±24.11●	-31.61±7.73 ●	-39.12±24.07●
autos	-13.14±2.31	-34.94±16.81●	-45.57±18.12●	-33.91±17.06●	-19.82±6.45 ●	-23.74±11.09●
balance-scale	-52.78±2.03	-31.75±1.51 ○	-31.75±1.51 ○	-34.78±3.10 ○	-67.11±2.71 ●	-14.04±3.99 ○
breast-cancer	-18.56±2.70	-20.47±5.23	-18.37±4.49	-18.17±3.60	-18.75±3.97	-17.47±2.83
breast-w	-11.17±3.39	-17.47±13.63	-18.28±14.16	-12.14±6.76	-9.75±5.08	-11.87±7.79
colic	-17.80±4.31	-34.42±17.34●	-30.63±11.38●	-26.22±9.35 ●	-19.04±6.30	-22.49±8.02 ●
colic.ORIG	-17.66±3.19	-38.50±17.60●	-21.24±5.74	-22.36±6.24 ●	-25.19±6.18 ●	-30.58±11.15●
credit-a	-28.06±4.92	-34.52±11.89	-28.79±8.10	-28.07±7.06	-29.82±7.91	-27.17±5.66
credit-g	-61.03±5.85	-62.44±23.22	-52.79±6.35 ○	-56.16±8.09	-63.26±9.89	-52.16±5.68 ○
diabetes	-43.05±4.79	-42.70±9.11	-40.78±7.49	-42.51±8.23	-45.44±7.22	-39.88±6.09
glass	-21.02±2.70	-31.06±9.62 ●	-24.08±5.42	-26.15±6.27 ●	-23.54±5.89	-25.14±7.38
heart-c	-15.85±3.68	-15.70±7.49	-13.91±6.71	-14.01±6.09	-13.97±5.46	-13.45±5.45
heart-h	-14.78±3.16	-14.73±5.94	-13.49±5.37	-12.96±4.06	-13.41±4.57	-13.21±4.59
heart-statlog	-14.00±3.33	-16.31±9.29	-12.25±4.96	-14.60±5.39	-11.68±3.61	-12.76±5.10
hepatitis	-6.81±2.51	-9.18±5.78	-8.53±5.98	-8.16±4.72	-7.20±3.69	-10.74±8.22
hypothyroid	-90.14±5.73	-98.23±14.58	-97.14±13.29	-93.72±12.69	-131.25±20.97●	-94.62±13.50
ionosphere	-10.77±3.04	-35.54±20.03●	-34.79±19.94●	-18.17±13.24	-13.45±7.42	-171.50±96.25●
iris	-3.63±1.35	-2.69±2.90	-2.56±2.35	-3.12±2.30	-3.04±2.25	-2.59±2.88
kr-vs-kp	-8.65±3.50	-28.01±18.07●	-93.48±7.65 ●	-60.27±7.38 ●	-58.41±6.49 ●	-37.71±8.08 ●
labor	-2.22±1.28	-1.03±2.27	-0.71±0.99 ○	-2.23±3.43	-1.61±0.90	-6.43±9.89
letter-2000	-193.65±10.88	-382.03±50.64●	-299.04±29.19●	-260.71±33.34●	-297.17±32.04●	-221.59±27.54
lymph	-7.75±2.64	-8.48±5.51	-6.22±3.96	-7.15±5.24	-6.90±3.21	-9.10±5.67
mushroom	-2.10±0.19	-0.14±0.14 ○	-105.77±23.25●	-0.19±0.45 ○	-0.05±0.34 ○	-0.00±0.00 ○
primary-tumor	-50.98±3.70	-74.19±14.56●	-65.56±8.27 ●	-69.75±8.85 ●	-93.51±12.35●	-81.10±16.98●
segment	-48.76±7.07	-111.94±45.14●	-124.32±33.74●	-40.15±13.46○	-58.30±12.72●	-37.99±12.83○
sick	-21.10±5.56	-45.55±19.82●	-46.05±11.99●	-28.91±8.80 ●	-27.64±8.62 ●	-33.45±10.45●
sonar	-11.91±2.45	-38.85±19.05●	-22.67±11.47●	-28.73±13.48●	-8.90±2.89 ○	-178.12±92.92●
soybean	-18.39±3.31	-28.63±15.19●	-26.25±11.03●	-8.06±3.84 ○	-16.67±5.16	-15.44±6.18
splice	-66.48±8.24	-47.11±13.57○	-46.53±12.85○	-46.89±11.95○	-181.79±19.56●	-126.34±54.97●
vehicle	-55.24±4.50	-137.97±32.69●	-172.12±27.55●	-57.52±10.16	-61.21±9.89	-68.11±11.51●
vote	-6.90±3.56	-7.35±5.41	-27.25±13.85●	-7.91±5.39	-10.94±7.44	-5.55±3.89
vowel	-71.55±6.18	-45.93±16.44○	-89.80±11.38●	-21.87±8.84 ○	-62.71±7.64 ○	-55.20±16.88○
waveform-5000	-318.55±12.98	-309.13±43.99	-378.00±32.64●	-254.80±23.42○	-305.25±18.78	-232.69±24.93○
zoo	-2.74±1.28	-1.29±1.68 ○	-1.22±1.06 ○	-1.07±1.44 ○	-1.64±0.95 ○	-2.29±3.41
average	-38.13±4.11	-54.32±15.89	-58.43±11.62	-40.40±8.89	-49.32±7.63	-48.90±15.21

●, ○ statistically significant degradation or improvement compared with C4.4

Table 5. Summary on *t*-test of experiment results: CLL comparisons on classic models.

Models	SVM	KNN-5	TAN	NB	NBTree
KNN-5	3/20/13				
TAN	8/21/7	10/22/4			
NB	5/16/15	7/13/16	3/19/16		
NBTree	3/19/14	6/18/12	2/22/12	6/24/6	
C4.4	12/17/7	12/20/4	10/19/7	17/14/5	15/16/5

Table 6. Summary on *t*-test of experiment results: AUC comparisons on decision tree variants.

Models	C4.5-L	C4.5-M	C4.5-LY	C4.5-L&B	C4.4-M	C4.4-LY	C4.4-B
C4.5-M	8/28/0						
C4.5-LY	14/18/4	11/17/8					
C4.5-L&B	22/14/0	18/18/0	10/23/3				
C4.4-M	15/21/0	9/26/1	10/19/7	3/26/7			
C4.4-LY	16/16/4	13/15/8	1/33/2	3/23/10	9/18/9		
C4.4-B	22/14/0	18/18/0	11/23/2	5/28/3	9/26/1	11/23/2	
C4.4	6/29/1	5/25/6	6/18/12	2/16/18	1/19/16	5/16/15	0/16/20

Table 7. Summary on *t*-test of experiment results: AUC comparisons on classic models.

Models	SVM	KNN-5	TAN	NB	NBTree
KNN-5	2/21/13				
TAN	7/23/6	17/16/3			
NB	4/21/11	10/19/7	4/21/11		
NBTree	1/29/6	9/25/2	3/27/5	7/27/2	
C4.4	2/16/18	3/18/15	2/14/20	5/10/21	2/14/20